

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	460241	(rotation\$4 or position\$4 or location\$4 or ang\$4) near3 (sensor or transducer or detector or encoder)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/04/26 15:18
L2	19305	(rotat\$3 same (phas\$4 near2 shift\$4))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/04/26 15:05
L3	3751	1 and 2	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/04/26 15:27
L4	16789	(phas\$4 near2 shift\$4) and 1	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/04/26 15:07
L5	265741	(alternat\$4 or sinusoid\$4) with (signal or wave)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/04/26 15:09
L6	6153	4 and 5	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/04/26 15:09
L7	709672	(sensor or transducer or detector or encoder) near4 signal\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/04/26 15:10
L8	5235	6 and 7	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/04/26 15:12

L9	460853	(revers\$4 or return\$4 or (turn\$4 adj back\$4) or counterclock\$4 or (rotat\$4 adj back\$4)) with (shaft or rotor or wheel or toothed or teeth or object)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/04/26 15:16
L10	626	8 and 9	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/04/26 15:16
L11	42814	(switch\$4 near3 signal) with (sensor or transducer or detector or encoder)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/04/26 15:19
L12	95	10 and 11	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/04/26 15:22
L13	195	3 and 11	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/04/26 15:32
L14	55	sinusoid\$4 and 13	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/04/26 15:28
L15	140	13 not 14	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/04/26 15:33